

W5 NUMERICAL ANALYSIS 2019-2020 FALL

OPTIMISATION I

CLASS EXERCISES

Class exercises will be completed and graded in class

EX 1 Following excel files(programs) are given investigate solutions

opt_golden_search.xlsx opt_secant.xlsx opt_bisection.xlsx	
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EX2 following one dimensional nonlinear optimiation programs are given investigate solutions.

```
public class opt_test
{
public static double golden(if_x f,double a,double b)
{
// find the minimum of the function
// note maximum f(x) = minimum (-f(x))
double epsilon;
double delta;
int print;
epsilon=0.001;
delta=0.002;
print=0;
double r1 = (Math.sqrt(5.0)-1.0)/2.0; // golden ratio
double r2 = r1*r1;
double h = b - a;
double ya = f.func(a);
double yb = f.func(b);
double c = a + r2*h;
double d = a + r1*h;
double yc = f.func(c);
double yd = f.func(d);
int k = 1;
double dp,dy,p,yp;
while ((Math.abs(yb-ya)>epsilon) || (h>delta))
{
k++;
if (yc<yd)
{
b = d;
yb = yd;
d = c;
yd = yc;
h = b - a;
c = a + r2 * h;
yc = f.func(c);
}
else
{
a = c;
ya = yc;
c = d;
yc = yd;
h = b - a;
d = a + r1 * h;
yd = f.func(d);
} //end of if
} //end of while
dp = Math.abs(b-a);
dy = Math.abs(yb-ya);
p = a;
yp = ya;
if (yb<ya)
{
p = b;
```

```

    yp = yb;
  }
  if(print==1)
  {System.out.println("x min = "+p+"ymin = "+yp+"error of x =" +dp+"error of y"+dy); }
  return p;
}
public static double quadratic_polynomial(if_x f,double x0,double x2)
{double x1=(x0+x2)/2.0;
return quadratic_polynomial(f,x0,x1,x2);
}
//secant optimisation method
public static double secant(if_x f,double x)
{ double eps=1.0e-10;
double y=f.func(x);
double dy=f.dfunc(x);
int miter=100;
int i=0;
while(Math.abs(y)>eps && i<miter)
{x=x-y/dy;
y=f.dfunc(x);
dy=f.dfunc2(x);
i++;
}
if(i>=miter)
System.out.println("i="+i+"results may not be valid");
return x;
}
//Bisection optimisation method f(x)=0 x=? given initial guess limits a and b
public static double bisection(if_x f,double a,double b)
{double b1=1.1*b;
double r=(a+b)/2.0;
double eps=1.0e-6;
int nmax=100;
int i=0;
while(Math.abs(f.dfunc(r))>eps && i<nmax)
{if(f.dfunc(a)*f.dfunc(r)<0) b=r;
else a=r;
r=(a+b)/2.0;
System.out.println("r="+r+"i="+i);
i++;
}
return r;
}
public static double quadratic_polynomial(if_x f,double x0,double x1,double x2)
{
double epsilon=1.0e-10;
double delta=1.0e-5;
int print=0;
return quadratic_polynomial(f,x0,x1,x2,epsilon,delta,print);
}
public static double quadratic_polynomial(if_x f,double x0,double x1,double x2,double epsilon,double delta,int print)
{
int maxit=100;
double f0 = f.func(x0);
double f1 = f.func(x1);
double f2 = f.func(x2);
double f3 = f2;
double x3 = 0;
double h = x1 - x0;
double k=1;
double dd=Math.abs(f1-f0);
while ((dd > epsilon) || (h > delta))
{
k++;
x3=(f0*(x1*x1-x2*x2)+f1*(x2*x2-x0*x0)+f2*(x0*x0-x1*x1))/
(2*f0*(x1-x2)+2.0*f1*(x2-x0)+2.0*f2*(x0-x1));
f3=f.func(x3);
if(x3 >= x0 && x3 < x1)
{x2=x1;f2=f1;x1=x3;f1=f3;}
else if(x3 >= x1 && x3 < x2)
{x0=x1;f0=f1;x1=x3;f1=f3;}
else if(x3 > x2)
{x0=x1;f0=f1;x1=x2;f1=f2;x2=x3;f2=f3;}
else if(x3 < x0)
{x0=x3;f0=f3;x1=x0;f1=f0;x2=x1;f2=f1;}
}
}

```

```

    dd=Math.abs(f1-f0);
    h=Math.abs(x1-x0);
    if(k>maxit) break;
    } //end of while
    if(print==1)
    {System.out.println("x = "+x3+"f = "+f3+"hata x = "+h+"hata f(x)=y "+dd); }
    return x3;
}
public static void main(String arg[])
{if_x ff=(x)->1.0/3.0*x*x*x-2*x+5;
double r1=secant(ff,1.0);
double r2=bisection(ff,1.0,3.0);
double r3=golden(ff,1.0,3.0);
double r4=quadratic_polynomial(ff,1.0,3.0);
System.out.println("r1="+r1+"r2="+r2+"r3="+r3+"r4="+r4);
Plot pp=new Plot(ff,0.0,3.0);
pp.plot();
if_x df=(x)->ff.dfunc(x);
Plot pp1=new Plot(df,0.0,3.0);
pp1.plot();
}
}

```

EX3 following multi dimensional nonlinear optimiation programs are given investigate solutions.

```

import java.util.Locale;
public class opt1_test
{
public static double[] gauss(double a[][],double b[])
{ //gauss elimination with partial pivoting
int n=b.length;
double x[]=new double[n];
double carpan=0;
double toplam=0;
double buyuk;
double dummy=0;
//gauss elimination
int i,j,k,p,ii,jj;
for(k=0;k<(n-1);k++)
{ //pivoting
p=k;
buyuk=Math.abs(a[k][k]);
for(ii=k+1;ii<n;ii++)
{ dummy=Math.abs(a[ii][k]);
if(dummy > buyuk) {buyuk=dummy;p=ii;}
}
if(p!=k)
{ for(jj=k;jj<n;jj++)
{ dummy=a[p][jj];
a[p][jj]=a[k][jj];
a[k][jj]=dummy;
}
dummy=b[p];
b[p]=b[k];
b[k]=dummy;
}
//Solving gauss elimination
for(i=k+1;i<n;i++)
{ carpan=a[i][k]/a[k][k];
a[i][k]=0;
for(j=k+1;j<n;j++)
{ a[i][j]-=carpan*a[k][j]; }
b[i] =b[i] -carpan*b[k];
}
}
//back substitution
x[n-1]=b[n-1]/a[n-1][n-1];
for(i=n-2;i>=0;i--)
{
toplam=0;
for(j=i+1;j<n;j++)
{ toplam+=a[i][j]*x[j];}
x[i]=(b[i]-toplam)/a[i][i];
}
}
}

```

```

    }
    return x;
    }
public static double[] newton_opt(if_xj f,double x[])
{ int k=x.length;
  int nmax=100;
  double tolerance=1.0e-10;
  double fx[];
  double dfx[][];
  double dx[];
  double total=0;
  for(int i=0;i<nmax;i++)
  { fx=f.dfunc(x);
    dfx=f.d2func(x);
    dx=gauss(dfx,fx);
    for(int j=0;j<k;j++)
      x[j]-=dx[j];
    total=0;
    for(int j=0;j<k;j++)
      total+=fx[j];
    if(Math.abs(total)<tolerance) return x;
  }
  return x;
}
public static String toString(double a[])
{int n=a.length;
  String s="";
  for(int i=0;i<n;i++)
    {s+=String.format(Locale.US,"%10g",a[i])+" ";}
  return s;
}
public static String toString(double a[][])
{int n=a.length;
  int m=a[0].length;
  String s="";
  for(int i=0;i<n;i++)
    { for(int j=0;j<m;j++)
      {s+=String.format(Locale.US,"%10g",a[i][j])+" ";}
      s+="\n";
    }
  return s;
}
//6-2. Nelder and Mead Simplex multivariable nonlinear optimization method
// Nelder & Mead 1965 Computer J, v.7, 308-313.
//_____
public static double[] nelder(if_xj fnelder,double a[],double da[],int maxiteration,double tolerance,int printlist)
{
    int i,j;
    double x[][]=new double[a.length+1][a.length];
    double p[][]=new double[a.length+1][a.length+1];
    for(i=0;i<x.length;i++)
    {for(j=0;j<x[0].length;j++)
      {if(i==j){x[i][j]=a[j]+da[j];p[i][j]=x[i][j];}
        else {x[i][j]=a[j];p[i][j]=x[i][j]; }
      }
      p[i][j] = fnelder.func(p[i]);
    }

    // Inlet variable definitions
    // fnelder : abstract multivariable function f(x)
    // x : independent variable set of n+1 simplex elements
    // maxiteration : maximum iteration number
    // tolerance :
    int NDIMS = x.length-1;
    int NPTS = x.length;
    int FUNC = NDIMS;
    int ncalls = 0;
    // construct the starting simplex ////////////////
    //double p[][]=new double[NPTS][NPTS]; // [row][col] = [whichvx][coord,FUNC]
    double z[]=new double[NDIMS];
    double best = 1E99;
    //////////////// calculate the first function values for the simplex ////////////////
    int iter=0;
    for (iter=1; iter<maxiteration; iter++)
    {

```

```

////////// define lo, nhi, hi (low high next_to_high ////////////
int ilo=0, ihi=0, inhi = -1; // -1 means missing
double flo = p[0][FUNC];
double fhi = flo;
double pavg, sterr;
for (i=1; i<NPTS; i++)
{
  if (p[i][FUNC] < flo)
    { flo=p[i][FUNC]; ilo=i;}
  if (p[i][FUNC] > fhi)
    { fhi=p[i][FUNC]; ihi=i;}
}
double fnhi = flo;
inhi = ilo;
for (i=0; i<NPTS; i++)
  if ((i != ihi) && (p[i][FUNC] > fnhi))
    { fnhi=p[i][FUNC]; inhi=i;}
////////// exit criteria ////////////
if ((iter % 4*NDIMS) == 0)
{
  // calculate the avarage (including maximum value)
  pavg=0;
  for(i=0;i<NPTS;i++)
    pavg+=p[i][FUNC];
  pavg/=NPTS;
  double tot=0;
  if(printlist!=0)
  { System.out.print(iter);
    for (j=0; j<=NDIMS; j++)
      { System.out.print(p[ilo][j]+" ");}
    System.out.println("");
  }
  for(i=0;i<NPTS;i++)
  { tot=(p[i][FUNC]-pavg)*(p[i][FUNC]-pavg);}
  sterr=Math.sqrt(tot/NPTS);
  //if(sterr < tolerance)
  { for (j=0; j<NDIMS; j++)
    { z[j]=p[ilo][j];}
    //break;
  }
  best = p[ilo][FUNC];
}

///// calculate avarage without maximum value /////

double ave[] = new double[NDIMS];
for (j=0; j<NDIMS; j++)
  ave[j] = 0;
for (i=0; i<NPTS; i++)
  if (i != ihi)
    for (j=0; j<NDIMS; j++)
      ave[j] += p[i][j];
for (j=0; j<NDIMS; j++)
  ave[j] /= (NPTS-1);
////////// reflect ////////////
double r[] = new double[NDIMS];
for (j=0; j<NDIMS; j++)
  r[j] = 2*ave[j] - p[ihi][j];
double fr = fnelder.func(r);

if ((flo <= fr) && (fr < fnhi)) // in zone: accept
{
  for (j=0; j<NDIMS; j++)
    p[ihi][j] = r[j];
  p[ihi][FUNC] = fr;
  continue;
}
if (fr < flo) //// expand
{
  double e[] = new double[NDIMS];
  for (j=0; j<NDIMS; j++)
    e[j] = 3*ave[j] - 2*p[ihi][j];
  double fe = fnelder.func(e);
  if (fe < fr)
  {

```

```

        for (j=0; j<NDIMS; j++)
            p[ihi][j] = e[j];
        p[ihi][FUNC] = fe;
        continue;
    }
    else
    {
        for (j=0; j<NDIMS; j++)
            p[ihi][j] = r[j];
        p[ihi][FUNC] = fr;
        continue;
    }
}
////////// shrink:
if (fr < fhi)
{
    double c[] = new double[NDIMS];
    for (j=0; j<NDIMS; j++)
        c[j] = 1.5*ave[j] - 0.5*p[ihi][j];
    double fc = fnelder.func(c);
    if (fc <= fr)
    {
        for (j=0; j<NDIMS; j++)
            p[ihi][j] = c[j];
        p[ihi][FUNC] = fc;
        continue;
    }
    else //////// shrink
    {
        for (i=0; i<NPTS; i++)
            if (i != ilo)
            {
                for (j=0; j<NDIMS; j++)
                    p[i][j] = 0.5*p[ilo][j] + 0.5*p[i][j];
                p[i][FUNC] = fnelder.func(p[i]);
            }
        continue;
    }
}

if (fr >= fhi) //
{
    double cc[] = new double[NDIMS];
    for (j=0; j<NDIMS; j++)
        cc[j] = 0.5*ave[j] + 0.5*p[ihi][j];
    double fcc = fnelder.func(cc);
    if (fcc < fhi)
    {
        for (j=0; j<NDIMS; j++)
            p[ihi][j] = cc[j];
        p[ihi][FUNC] = fcc;
        continue;
    }
    else //////////
    {
        for (i=0; i<NPTS; i++)
            if (i != ilo)
            {
                for (j=0; j<NDIMS; j++)
                    p[i][j] = 0.5*p[ilo][j] + 0.5*p[i][j];
                p[i][FUNC] = fnelder.func(p[i]);
            }
    }
}
}
return z;
}

public static double[] nelder(if_xj fnelder,double a[],double da[],double tolerance)
{return nelder(fnelder,a,da,500,tolerance,0);}

public static double[] nelder(if_xj fnelder,double a[],double da[])
{return nelder(fnelder,a,da,500,1.0e-10,0);}

public static double[] nelder(if_xj fnelder,double a[])
{

```

```

        double [] da=new double[a.length];
        for(int i=0;i<a.length;i++) da[i]=0.1*a[i];
        return nelder(fnelder,a,da);
    }

```

```

public static void main(String arg[])
{if_xj ff=(double x[])->3.0*x[0]*x[0]-4.0*x[0]*x[1]+2.0*x[1]*x[1]-x[0]-x[1];
double xx[]={1,2};
double r1[]=newton_opt(ff,xx);
double r2[]=nelder(ff,xx);
System.out.println("r1=\n"+toString(r2)+"\nr2=\n"+toString(r2));
surfacePlot pp1=new surfacePlot(ff,-2.0,2.0,-2.0,2.0);
pp1.plot();
}
}

```

```

/*
 * To change this template, choose Tools | Templates
 * and open the template in the editor.
 */

/*
 * Example.java
 *
 * Created on Mar 13, 2010, 2:46:54 PM
 */
/**
 *
 * @author siva
 */
//changed by M. Turhan Coban
import java.awt.*;
import javax.swing.*;
import javax.swing.JPanel;
import javax.swing.JLabel;
import java.awt.BorderLayout;
import java.awt.FlowLayout;

public class surfacePlot2 extends javax.swing.JFrame {
    ExampleSurfaceModel2 model;
    SurfaceCanvas canvas;
    JPanel southPanel;
    Container c;

    public void plot()
    {
        c=this.getContentPane();
        c.setLayout(new BorderLayout());
        southPanel = new JPanel(new FlowLayout(FlowLayout.CENTER, 50, 5));
        southPanel.add(new JLabel("Rotate: Mouse Click & Drag"));
        southPanel.add(new JLabel("Zoom: Shift Key + Mouse Click & Drag"));
        southPanel.add(new JLabel("Move: Control Key + Mouse Click & Drag"));
        add(southPanel, BorderLayout.SOUTH);
        this.setSize(1000,1000);
        add(canvas, BorderLayout.CENTER);
        this.repaint();
        this.setVisible(true);
    }

    public surfacePlot2(if_xj f,double x0,double xn,double y0,double yN,double z0,double zN,
        String xLabel, String yLabel,String zLabel)
    { model = new ExampleSurfaceModel2(f,x0,xn,y0,yN,z0,zN,xLabel,yLabel,zLabel);
      canvas = new SurfaceCanvas();
      canvas.setModel(model);
      canvas.setSize(1000,1000);
      canvas.setVisible(true);
    }

    public surfacePlot2(if_xj f,double x0,double xN,double y0,double yN,double z0,double zN)
    { String xLabel="x";
      String yLabel="y";
      String zLabel="z";
      model = new ExampleSurfaceModel2(f,x0,xN,y0,yN,z0,zN,xLabel,yLabel,zLabel);
      canvas = new SurfaceCanvas();
      canvas.setModel(model);
    }
}

```

```

        canvas.setSize(1000,1000);
        canvas.setVisible(true);
    }
    public surfacePlot2(if_xj f,double x0,double xN,double y0,double yN)
{   String xLabel="x";
    String yLabel="y";
    String zLabel="z";
    double z0=9.9e50;
    double zN=-9.9e50;
    int n=100;
    double dx=(xN-x0)/n;
    double dy=(yN-y0)/n;
    double zz;
    double x1=0,y1=0;
    for(int i=0;i<n;i++)
    {for(int j=0;j<n;j++)
    {   x1=x0+i*dx;y1=y0+j*dy;
        double xx[]={x1,y1};
            zz=f.func(xx);
            if(zz<z0) z0=zz;
            if(zz>zN) zN=zz;
        }
    }

    model = new ExampleSurfaceModel2(f,x0,xN,y0,yN,z0,zN,xLabel,yLabel,zLabel);
    canvas = new SurfaceCanvas();
    canvas.setModel(model);
    canvas.setSize(1000,1000);
    canvas.setVisible(true);
}

    public surfacePlot2(if_xj f,double x0,double xN,double y0,double yN,String xLabel,String yLabel,String zLabel,int N)
{
    double z0=9.9e50;
    double zN=-9.9e50;
    int n=100;
    double dx=(xN-x0)/n;
    double dy=(yN-y0)/n;
    double zz;
    double x1=0,y1=0;
    for(int i=0;i<n;i++)
    {for(int j=0;j<n;j++)
    {   x1=x0+i*dx;y1=y0+j*dy;
        double xx[]={x1,y1};
            zz=f.func(xx);
            if(zz<z0) z0=zz;
            if(zz>zN) zN=zz;
        }
    }

    model = new ExampleSurfaceModel2(f,x0,xN,y0,yN,z0,zN,xLabel,yLabel,zLabel);
    canvas = new SurfaceCanvas();
    canvas.setModel(model);
    canvas.setSize(1000,1000);
    canvas.setVisible(true);
}

public static void main(String args[]) {
    if_xj f=(double x[])->x[0]*x[0]+x[1]*x[1];
    surfacePlot2 p=new surfacePlot2(f,-5.0,5.0,-5.0,5.0);
    p.plot();
}
}

```

```

/*
 * To change this template, choose Tools | Templates
 * and open the template in the editor.
 */
//package net.sf.surfaceplot;
/**
 * @author salagarsamy
 */
// Adapted by M. Turhan Coban
public class ExampleSurfaceModel2 implements ISurfacePlotModel
{   float x[],y[],z[];
    String xlabel,ylabel,zlabel;
    float xmin,xmax,ymin,ymax,zmin,zmax;
    boolean boxed,mesh,scalebox, displayxy,displayz,displaygrid;
    int calcddiv,dispddiv;
}

```



```

if_xj f;
public ExampleSurfaceModel2(if_xj f1,double xmin,double xmax,double ymin,double ymax,double zmin,double zmax)
{f=f1;xmin=(float)xmini;xmax=(float)xmaxi;ymin=(float)ymini;ymax=(float)ymaxi;
zmin=(float)zmini;zmax=(float)zmaxi;
boxed=true;
mesh=true;
scalebox=false;
displayxy=true;
displayz=true;
displaygrid=true;
calcdiv=80;
dispdiv=80;
xlabel="X";
ylabel="Y";
zlabel="Z";
}
public ExampleSurfaceModel2(if_xj f1,double xmin,double xmax,double ymin,double ymax,double zmin,double zmax,String
lx,String ly,String lz)
{f=f1;xmin=(float)xmini;xmax=(float)xmaxi;ymin=(float)ymini;ymax=(float)ymaxi;
zmin=(float)zmini;zmax=(float)zmaxi;
xlabel=lx;
ylabel=ly;
zlabel=lz;
boxed=true;
mesh=true;
scalebox=false;
displayxy=true;
displayz=true;
displaygrid=true;
calcdiv=100;
dispdiv=100;
}
public float calculateZ(float x, float y)
{ double z[]={x,y};
return (float)f.func(z);
}

public double calculateZ(double x, double y)
{ double z[]={x,y};
return f.func(z);}
public double calculateZ(double z[])
{ return f.func(z);
}
public int getPlotMode()
{return ISurfacePlotModel.PLOT_MODE_SPECTRUM;}

public boolean isBoxed()
{return boxed;}

public boolean isMesh()
{return mesh;}

public boolean isScaleBox()
{return scalebox;}

public boolean isDisplayXY()
{return displayxy;}

public boolean isDisplayZ()
{return displayz;}

public boolean isDisplayGrids()
{return displaygrid;}

public void setCalcDivisions(int calcdivi )
{calcdiv=calcdivi;}
public int getCalcDivisions()
{return calcdiv;}
public void setDispDivisions(int dispdivi )
{dispdiv=dispdivi;}
public int getDispDivisions()
{return dispdiv;}
public void setXMin(double xmin)
{xmin=(float)xmini;}
public float getXMin()

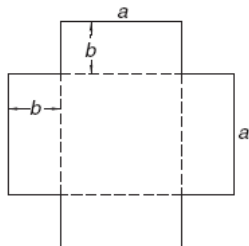
```

```

        {return xmin;}
public void setXMax(double xmaxi)
    {xmax=(float)xmaxi;}
    public float getXMax()
    {return xmax;}
public void setYMin(double ymini)
    {ymin=(float)ymini;}
    public float getYMin()
    {return ymin;}
public void setYMax(double ymaxi)
    {ymax=(float)ymaxi;}
    public float getYMax()
    {return ymax;}
    public void setZMin(double zmini)
    {zmin=(float)zmini;}
    public float getZMin()
    {return zmin;}
    public void setZMax(double zmaxi)
    {zmax=(float)zmaxi;}
    public float getZMax()
    {return zmax;}
    public void setXAxisLabel(String xlabeli)
    {xlabel=xlabeli;}
    public String getXAxisLabel()
    {return xlabel;}
    public void setYAxisLabel(String ylabeli)
    {ylabel=ylabeli;}
    public String getYAxisLabel()
    {return ylabel;}
    public void setZAxisLabel(String zlabeli)
    {zlabel=zlabeli;}
    public String getZAxisLabel()
    {return zlabel;}
}

```

EX5:



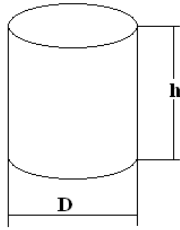
In order to make a carton box, the shape above should be used. After bending from the dotted line the volume of the box will be 1 m^3 . In order to spend the minimum amount of the carton, what a and b dimensions should be?

EX 6: Find the minimum of function

$$f(x) = \frac{15x}{(4x^2 - 3x + 4)} \quad f \text{ is in the range of } 0 \text{ to } 10.$$

HOMEWORK EXERCISES

Homework exercises will be done at home and will bring to next friday class printed no late exercises will be excepted.



W5HW1:

One of the very basic optimization problem is the minimum cost of container problem. The cost of a box usually is a function of the surface area. Therefore we should minimize the area for a given volume For example if the volume of the container

$V=0.5 \text{ liter}=0.5 \times 10^{-3} \text{ m}^3 :$

Volume $V = \frac{\pi D^2}{4} h$ or from this equation h, height is obtained as $h = \frac{4V}{\pi D^2}$.

Surface area of the cylinder : $A = 2 \frac{\pi D^2}{4} + \pi D h = \frac{\pi D^2}{2} + \frac{4V}{D}$.

Analytical solution of the minimization problem

$\frac{dA}{dD} = \pi D - \frac{4V}{D^2} = 0$

$D = \sqrt[3]{\frac{4V}{\pi}}$. From here solution is $D = \sqrt[3]{\frac{4 * 0.5 \times 10^{-3}}{\pi}} = 0.086025401 \text{ m}$ and .

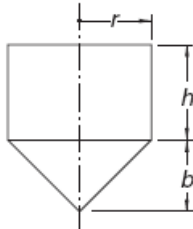
$h = \frac{4 * 0.5 \times 10^{-3}}{\pi D^2} = 0.086025401 \text{ m}$.

Now obtain this results by using numerical optimization methods.

For the range of $0.01 \leq D \leq 0.2$

- a) Graphic method
- b) Golden ratio (Fibonacci)
- c) Secant method
- d) Second degree polynomials

W5HW2:



It is desired to have volume of the cone base shape shown in the figure as 1 m^3 . Calculate r,h and b dimensions to minimise the surface area.

$V = \pi r^2 \left(\frac{b}{3} + h \right)$

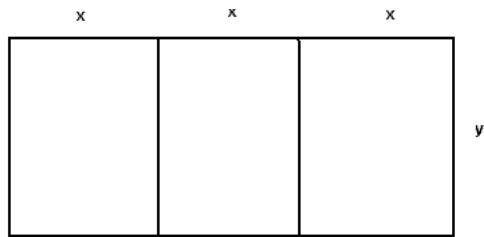
$S = \pi r \left(2h + \sqrt{b^2 + r^2} \right)$

W5HW3 :

Find the minimum of

$f = 25x^2 - 12x^4 + 6xy + 25y^2 - 24x^2y^2 - 12y^4$

W3HW4: A farmer needs 150 meters of fencing to fence three adjacent gardens. What would be maximum area of each garden, and what would be values of x and y



$$4y + 6x = 150$$

$$y = 37.5 - 1.5x$$

$$A(x) = 3(37.5 - 1.5x)x = 112.5x - 4.5x^2$$

$$\frac{dA(x)}{dx} = 112.5 - 9x = 0$$

$$x = 12.5 \quad y = 18.75$$

$$A = 703.125 \text{ total of 3 garden}$$

Calculate by using a numerical method